GEVEA



NSL60 Motor operating mechanism

1. General

Motoroperating mechanism NSL60 are designed for operation of medium voltage overhead line – and substation switches. The motoroperating mechanism can be operated locally with push buttons or remotely via remote control systems. The motoroperator can also me manually operated with a crank handle.

The NSL60 motoroperator is suitable for switches with a reciprocal operating movement and with a requirement of a maximum operating force of 6500N.

2. Characteristic features

- ·Large maximum operating force, 6,5kN
- ·Operational reliability
- Compact design
- •Easy to maintain and service
- ·High reliability and durability

3. Motoroperator type, type designations

NSL60	-1 or -2	/24V or /220VDC						
	1 – Small cabinet 2 – Large cabinet	Motor- and auxiliary circuit voltage						

Example.

1. Motoroperator NSL60-1/220VDC

Motordrive assembled in small cabinet, motor and auxiliary circuit voltage 220Vdc

2. Motoroperator NSL60-2/24VDC

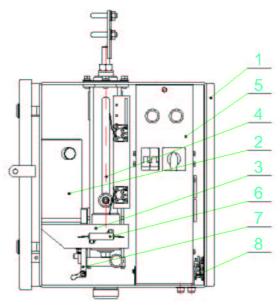
Motordrive assembled in large cabinet, motor and auxiliary circuit voltage 24VDC

3. Construction

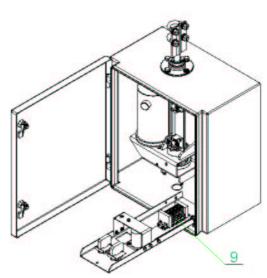
The motoroperating mechanism consists of

- ·Gearbox mechanism with motor
- •Limit switches that sets the travel of the mechanism
- •Terminal for connection to motor- and auxiliary circuits
- Mechanical interlock
- •Auxiliary circuit with contactors and local switches
- •Anti condensation heater with thermostat

- [1] Housing
- [2] Motor
- [3] Gearbox
- [4] Tension member
- [5] Control panel
- [6] Anti condensation heater
- [7] Mechanical interlock
- [8] Limit switch for door
- [9] Connection terminals



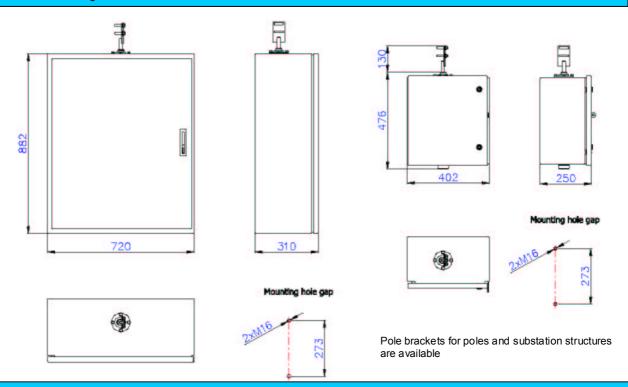
The housing is manufactured in aluminium and painted with an epoxy colour. The door are sealed with a rubber gasket. The cabinet have a encapsulation degree of $\mathbb{P}54$



5. Technical characteristics

No.	Characteristic	Value								
1	Rated voltage	24VDC	220VDC, 230VAC							
2	Rated power	300W								
3	Rated current	19A	2,2A							
4	Maximum operating force	6,5kN								
5	Operating time	Approx. 4 sec.								
6	Max. connector section	2,5m²								
7	Weight	Approx. 20kg								
8	Mechanical endurance	2000 operations								

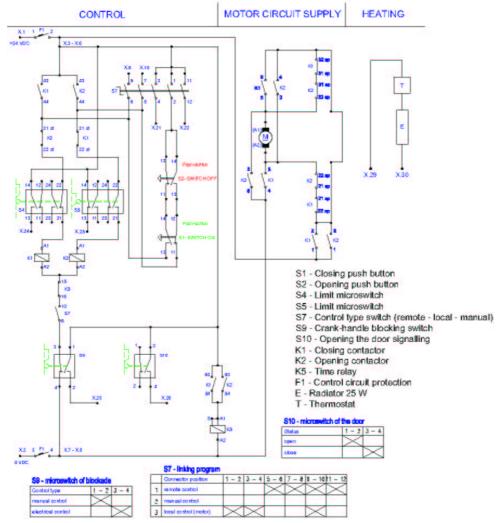
6. Dimensional drawings



7. Connection terminals

F2 - 1	K1.4	F1.1	67 6	27-1	87.4	87.19	XN-12	XN-8	4-42	510.2	01-NX	K5-A2	K1-5	87-11	\$4-3	XN-11	K1-1	K1-3	-	L
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	31	32
+Uz=24Vdc	-Uz=24Vdc	motor +Uz=24Vdc	control	switch-off remote control	switch-on local control	mapping remote control	mapping blocking	mapping 1 bit status	mapping 1 bit status	mapping opening the	door mapping -24Vdc	control	F1.2	XN-7	\$10-1	K1 - 13	M. A2	M-A1	Muce	2207/

8. Circuit diagram



Note: Status of S4 and S5 microswitch comply with open position of HV switching device

X - Terminal strip

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